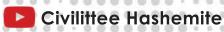


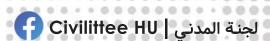
دفتر ابلاید

د. يحيى الرواش

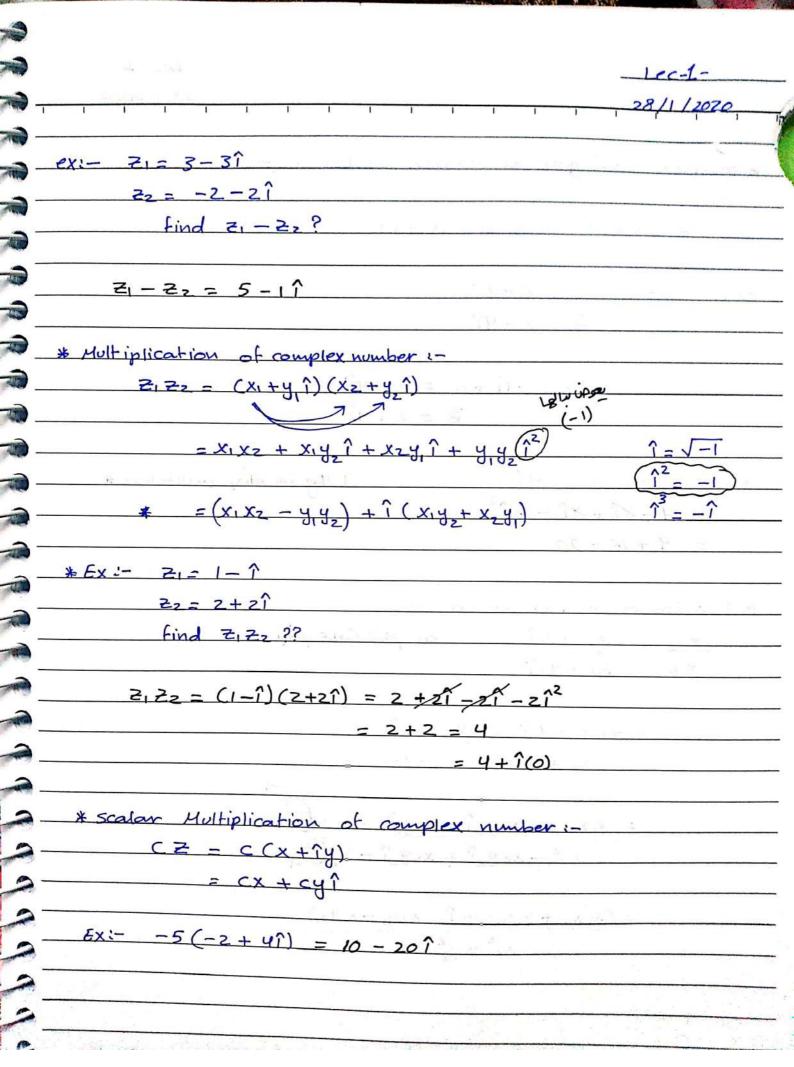
إعداد : روابي ابو غزالة

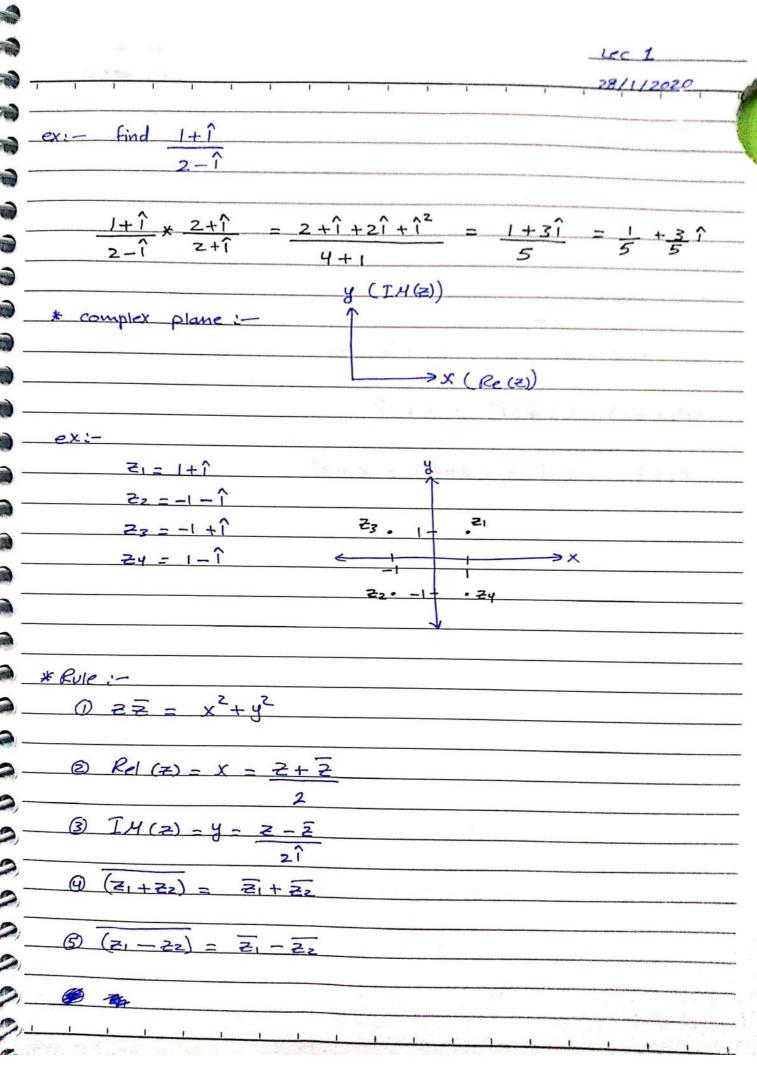




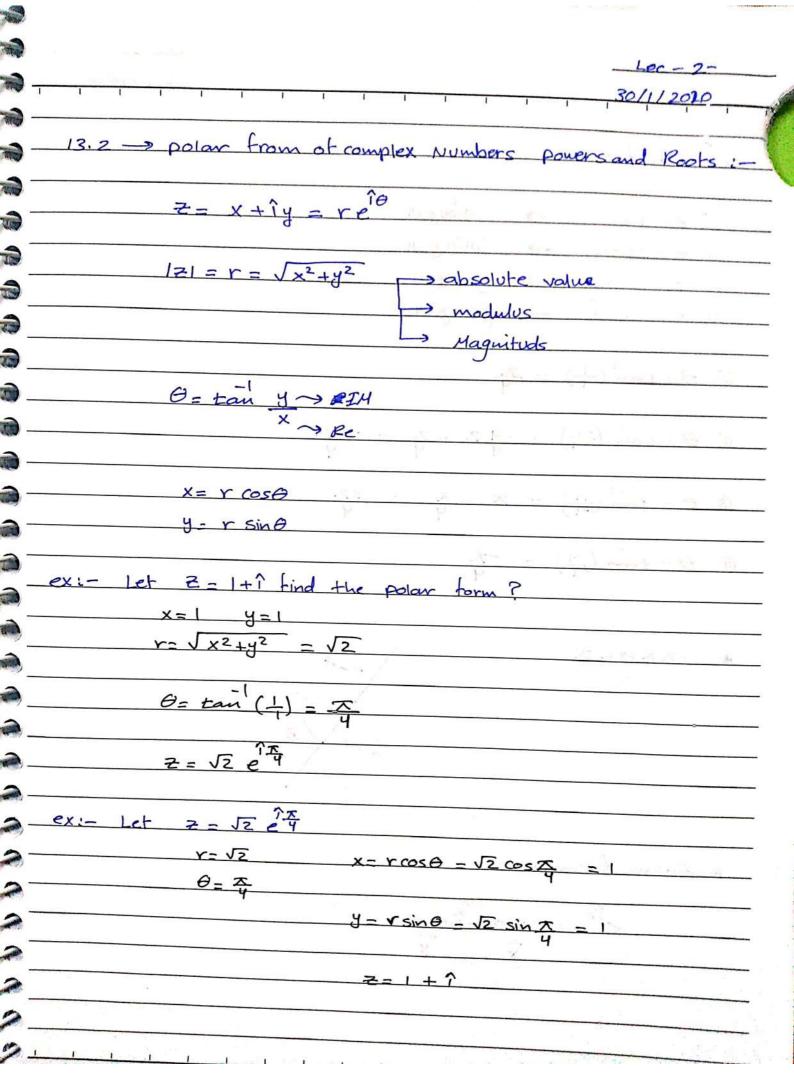


	_Lec-t-
	28-1/2020
1	
	(Applied)
_	
) _	13.1 -> complex Numbers and their Geometric Representation
—	13:1 - S complex Numbers and Their Chamerric representation
_	2
<u> </u>	$x^2 = -1$ \longrightarrow $x = \pm \sqrt{-1}$ $= \pm \hat{1}$ $= \pm \hat{d}$
-	
_	* any complex Number can be written In the form :-
_	S 7
_	$\frac{Z=x+\hat{y}}{y=IH} = \frac{X=Re\left\{z\right\}}{y=IH}$
) –	9 = IH {=}
) -	the state of the s
<u> </u>	$ex:- Z_1 = 1+1 = 1+1(1)$
ラ > -	X=
-	¥=1
	Zz=-3-41
	X= -3
	7=-4
	23=5=5+î(0)
	Y=5
-	y = 0
3	Character II Well All a Santa
3	Zy= -41 = 0-41
3	×-0
2	
	y = -4
2	
ъ,	VI a A A
7	





find (21+22), 21+22 ?? (Z1+Z2) = (3 \$3î) = 3+3î 至1+至2 = (一1) + (2+41) = 3+31

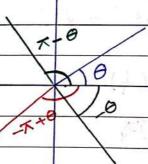


Jec 2 30/1/2020

exi- find 0 for

$$3\theta = \tan\left(\frac{+1}{-1}\right) = \pi - \pi = 3\pi$$

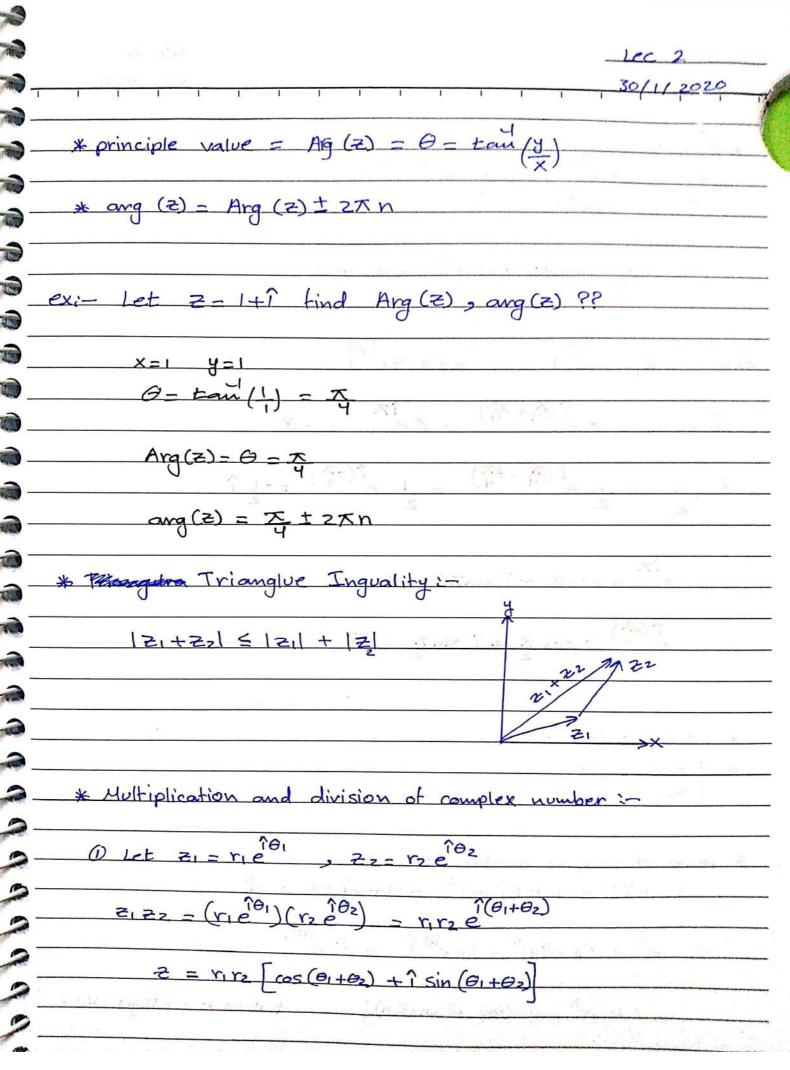




* Eular formula :-

$$e^{\hat{i}\theta} = \cos\theta + \hat{i}\sin\theta$$

 \overline{x} \overline{y}



Lec 2 30/1/2020 $= \frac{r_1}{r_2} \hat{\theta}(\theta_1 - \theta_2)$ $\frac{2}{r_2} = \frac{r_1}{r_2} \left[\cos(\theta_1 - \theta_2) + \hat{1} \sin(\theta_1 - \theta_2) \right]$ 1) 2122 = 8 e (() + 3x) 8e = $= \cos X + \hat{1} \sin X = -1$?(=\frac{\Z}{2}) = cos \(\times + \hat{1} \sin \(\times - \hat{1} \) * 12,22 = 12,1 1221 * power of complex number :- $(1+\hat{1})^2 = 1+2\hat{1}+\hat{1}^2 = 1+2\hat{1}-1=2\hat{1}$ = r e ion \Rightarrow $z^n = (x+iy)^n - (re^{i\theta})^n$ = r [cos (On) +isin (On)] but -> n = integer Value

30/1/2010 ex:- find (1+1) =? n=10 integer x= √2 θ= tan 1 = Τ THE (C) (1+1) - (2e4) = 5 1 4x10 32 e \$2 (0) 1 = 32 [cos 5x + 1 sin 5x] = 32 [0+1] = 321 * Demoiver formula :-[eîo]" = eî[on] $\left[\cos\theta + i\sin\theta\right]^{n} = \cos(\theta n) + i\sin(\theta n)$ * Root of complex number:-V= = Vx+14 = Vr [cos \text + 7 sin \text + 2xk] $\frac{1}{\sqrt{x^2+y^2}} = \frac{1}{\sqrt{x^2+y^2}} = \frac{1}{\sqrt{x^2+$ n= integer K=0,1,2--- (n-1)

Whe 1st Root at
$$k=0$$

$$= \sqrt[3]{1} \left[\cos \frac{0+2\pi \cdot 0}{3} + i \sin \frac{0+2\pi \times 0}{3} \right]$$

$$\frac{3\sqrt{1}\left[\cos O + 2\pi x^2 + i\sin O + 2\pi x^2\right]}{3}$$

$$= 1 \left(\cos \frac{4x}{3} + \hat{1} \sin \frac{4x}{3} \right)$$

€ Isecond root -> \$\frac{1}{5} [cos 2\times + \times \sin 2\times]

Q 4d root at K=3 -> TT [cos 6x +7 sin 6x] (3) 5th root at K=4 → 5/1 [cos 8x + i sin 8x]

& OT => x=1 y=0 r=1 0=0 n=6

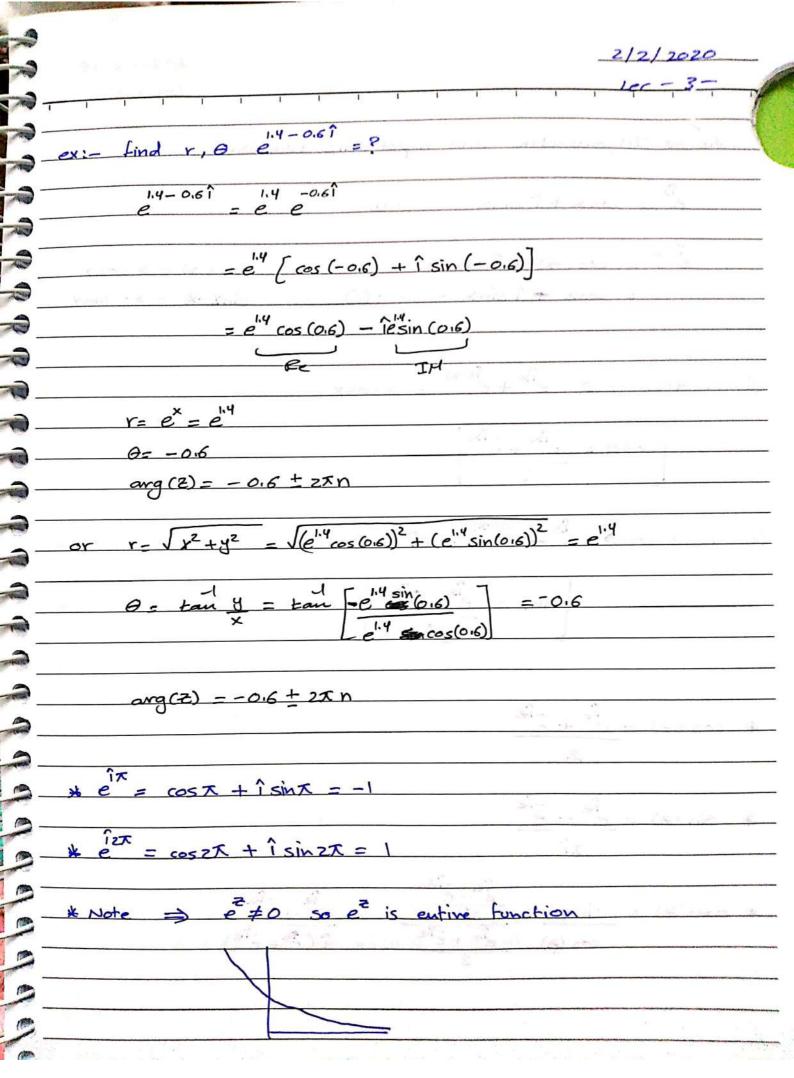
->6/1 [cos 2x + î sin 2x] = cos x +î sin x 2 2nd root at K=1

B 3rd root at K=2 → 6√1 [cos 4x + î sin 4x] = cos 2x +î sin 2x

(9) 4th root at K=3 -> 6 TI [cos 6x + i sin 6x] = cosx +i sin x = -1

(5) 5th root at k=4 → 6√1 [cos 8x + i sin 8x] = cos 4x + i sin 4x

@ 6th root at K=5 -> 6/1 [cos 10x +7 sin 10x] - \$cos 5x +7 sin 5x



		12 -121
* cot (Z)= _	= cos = =	- 1(e=+=12)
		- T-

$$tam(z) = cos z = (c + e)$$

$$tam(z) = sin z = e^{-1z}$$

$$* Sec (Z) = 1 = 2$$

$$cos(Z) = 1^{1}Z - 1^{2}Z$$

$$4 \quad \csc(z) = 1 = 2\hat{1}$$

$$\sin(z) = \hat{1}z - \hat{1}z$$

$$\# \left[\sin(z)\right] = \cos(z)$$

* hyperbolic function:-

 $O \cosh(z) = \frac{e^z + e^z}{2}$

(2) $\sinh(z) = \frac{z^2 - z^2}{2}$

(3) (cosh (z)) = sinh (z)

2

2

(2) [sinh (2)] = cosh (2)

G tanh (Z) = $\frac{\sinh(z)}{\cosh(z)} = \frac{e^{z} - e^{z}}{e^{z} + e^{z}}$

 $G \operatorname{sech}(2) = 1 - 2$ $\operatorname{cosh}(2) = \frac{2}{2} + \frac{2}{2}$

(8) (sch(7) = 1) = 2

* complex number trigonometric and hyperbolic function are related
* cosh (12) = cos (2)

* sinh (12) = 1 sin (2)

 $\cos(\hat{a}) = \cosh(2)$

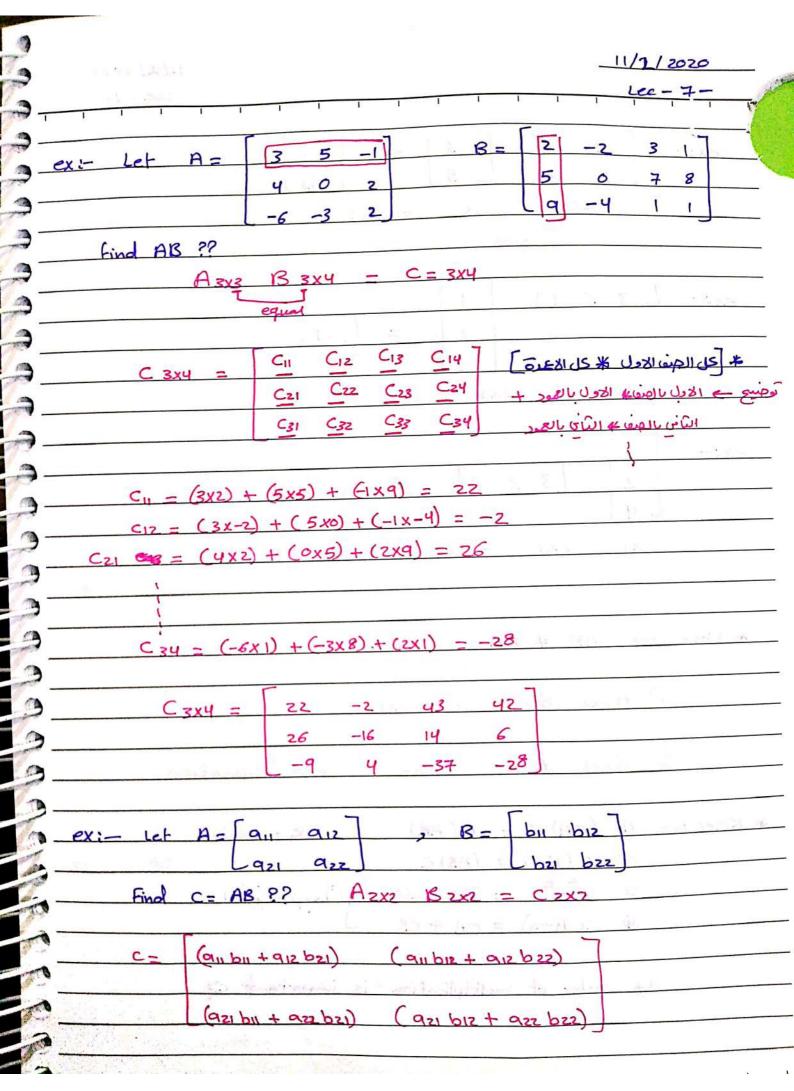
* sin(12) = 1 sinh (2)

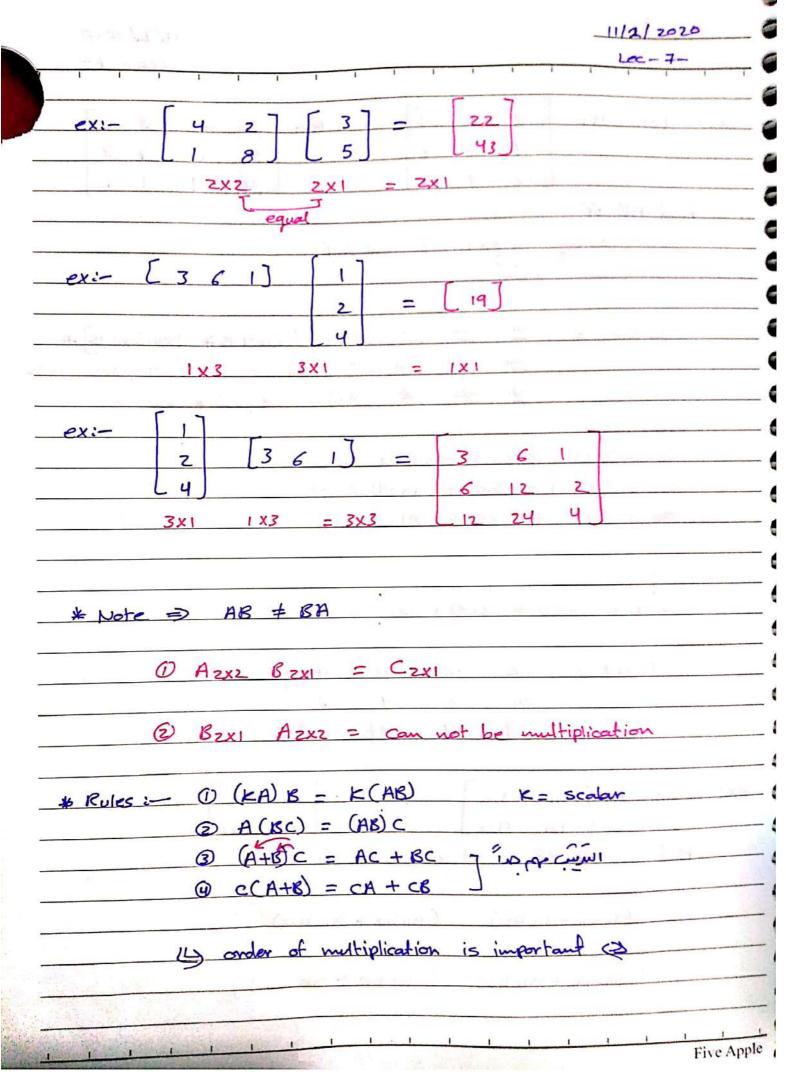
4/2/2020 * find Lu(1) = ?? m(1) = m(1+1(0)) = mr+ îg = m1 + î[0 ± 2xn] = î[zxn] * ex :- find Ln(-4) = ?? Ln [-4+ îco] x=-4 y=0 r=4 0=x c Ln [-4+10] = Ln4+1[x+zxn] * ln (2122) = ln 21 + ln 22 16 lu (21) = lu Z1 - lu Z2 * principle value of en (2) is called Ln (2) Ln (Z) = eu(Z) + î Arg (Z) -en(2) = In(2) + 2xn? * ex= find Ln (2î) ?? lu [0+î(z)] = lu(r)+î0

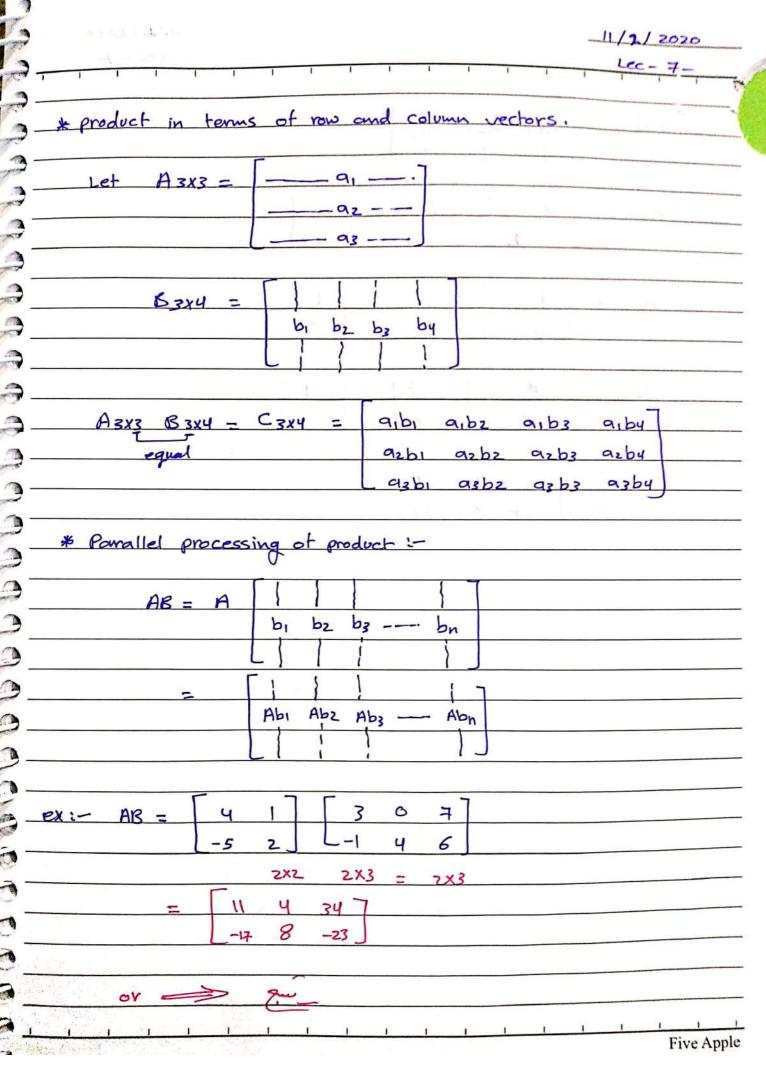
6/2/2020 $ext = find (1+1)^{2-1} = ??$ $(1+\hat{1})^{2-\hat{1}} = e^{(1+\hat{1})^{2-\hat{1}}}$ $(2-\hat{1})e^{(1+\hat{1})}$ en (1+1) = eur + îts - en 12 + 1/2 + 2xn (2-1) Env2 + 2+2xn] X3+143 = 2 (2-1) [en 12 +î [] + 2xn] x3+1y3 x3 1y3 = e Cosy + i siny] = e cosy, + ex3 siny 1 * principle value for (1+1) -> happend at n=0 (2-1) (env2 +1 4) 2 en/2 + 21 4 - jen/2 + 4 = = (2 en/2+4]+1(=-en/2)

LEEL ST

		9/2/2020		
1 1 1 1	1 1 1 1 1 1	lec-6-		
7.1 -> Matrix, vector, addition and scalar multiplication:				
ALCON ALCON STORY				
or function which we will enclose				
in brakets.				
674 7-9 = 1 574 et la				
A =	1 2 3 S = X	y]		
	4 6 7 Lsin	x cosy		
Toward	18 - 1779 - 1798 - 20 - 20 - 20 - 20	s ghill and		
$A = \begin{bmatrix} a_{11} \\ \vdots \\ a_{1n} \end{bmatrix}$.x			
92	922 923	,		
	1 932 933	tra tx		
	I water it was a let .			
=> size of matrix = mxn				
row J I column				
	E.W. 20			
> vector is a matrix with one row of one column.				
	2.8			
⇒ V= V				
V	⇒ column vector	Village g		
LVZ				
5.700	55(9)			
3x1				
⇒ b = [b1 b2 b3] ⇒ Row vector				
1 x 3				
	The state of the s			







Lec - 8-

* squar matrix -> matrix that has some column and raw.

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

* symmetric matrix > iff AT = A

$$ex := A = \begin{bmatrix} 20 & 120 & 200 \\ 120 & 10 & 150 \\ 200 & 150 & 30 \end{bmatrix}$$

$$A^{T} = \begin{bmatrix} 20 & 120 & 200 \\ 120 & 10 & 150 \\ 200 & 150 & 30 \end{bmatrix}$$

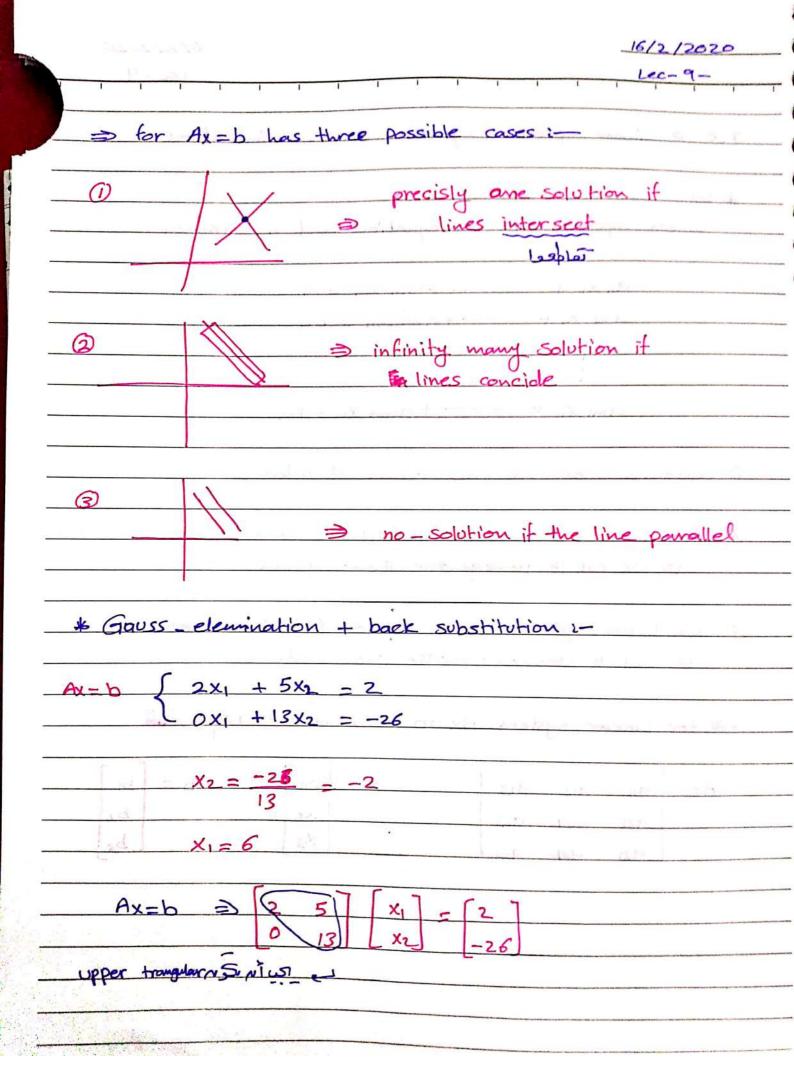
So A=AT => matrix is symmetric

* skew - symmetric iff AT = -A

ex:- Let
$$A = \begin{bmatrix} 0 & 1 & -3 \\ -1 & 0 & -2 \\ 3 & 2 & 0 \end{bmatrix}$$

AT = - A => then A is skew-symmetric

1			161-1
3	25 25 4 10		6/2/2020
)_	10 - 35 1		Lec-9-
3_			
<u> </u>	7.3 -> Linear system of equabing	on Gauss-dime	nation
199			
	* Let	151	
600	Linear system with m-equ	vation and no	nknown
)	911 X1 + + 0	lin Xu = bi	
3	921 X1++92		
_	1	n An - DZ	
<u> </u>			
_		10	
	amixi + +	amn In = bn	
3 —			
3 -	1) System is linear, X1, X2	· Xn of order I	
3 -			
9-	3 for Linear system with all	(bj) are zero	
3-	⇒ we call it Homogenouse	linear system	
-			
_	3 for linear system with at 1	est one (bj) is no	ot zero
	€ call it Nonhomogenouse		
		2 - 126 4	N. S
3_	⇒ for Linear system Ax = b	> matrix (1) au	م الما
3_			100
3-	A = 911 912 913	x= [x1]	h - [h.]
% _	वय वय वय	XZ	bz
_	931 934 923	X3	bz
_			5-3
	The state of the s	6 I SI	
	424		7.7
	AND AND ALL MANAGEMENT OF THE PARTY OF THE P		
-			



Find the XI > X2 ?? $-4x_1 + 3x_2 = -30$ solution A= [AIb] 2 -> Pivot or inplication لازم أحص على هذه المعادلات بحين في كل معادلة ينقق متقسر

. 55 25 2 SM	18/2/2020
	lec-10-
& elemintary Row opration for matrix:	
+	
@ Interchange of two rows	= +
(2) addition of constant multiple of one Row	to another Row,
3 Multiplication of one Row by non-zero	constant C
S MULTIPITE COLOR OF OTHE FOLLOW	
=> has no effected of mabrix A or the solution	
has no effected of marrix 17 of the	*
ex:- a11 a12 a13 [x1] b1]	
$921 \ 922 \ 923 \ X2 = b2$	
Y- h-	1
<u> </u>	
azi azz azz XI bz.]	8
a_{33} a_{12} a_{13} a_{22} a_{23} a_{23} a_{24} a_{25} a_{25}	
911 912 913 [X3] [D31]	
3 both system has same solution.	
	9
* over deterimined linear system :-	
if it has more equation than unknowns	
* determined linear system	
if number of equation equal number of unknown	wn S
* under determinal linear system	
if it has fewer equation than unknowns	

		18/2/2020
	1 1 1 1 1 1 1 1 1 1	Lec-10-
* Consis	ant linear system:	
if i	thas at lest one solution	
	palici se ale o se debes , d. P.	
* In-	consistent linear system	7
iF	it has no-solution	
ex:-	with infinitly many solution	<u> </u>
	3x1 + 2x2 +2x3 - 5x4 = 8	
	0.6 x1 + 1.5 x2 + 1.5 x3 - 5.4 x4 = 2.7	10.00
_	$1.2 \times 1 - 0.3 \times 2 - 0.3 \times 3 + 2.4 \times 4 = 2.1$	
))		
, F	ind X1, X2, X3, X4 ??	هذا يوم ٣ معادلا
3		emined linear System
O A		
9	No. 11 Section 1981	o. o. 382
3	3 2 2 -5 \ X1 \ [87	L 137
3	0.6 1.5 1.5 -5.4 12 = 27	o d
3	L12 -03 -03 24 X3 21.	
3	LXy	
3 2 A=	[A:b]	• 2
3-		
0	3 2 2 -5 18 -> Pivot	
	0.6 1.5 1.5 -5.4 2.7	
	J12 7013 -013 214 / 21	
		a total da dame
Sala at Se		
THE BY ME		

20/2/2020 R 3 0 0. 3 B= Rank = 2 2 0 00 0 3 2 & Rank = 3 2

and uniqueness 7.5 -> Solution of linear system: existance For linear system Ax=b A= CA:b] m- equation n- unknowns 1) existence: - linear system is consistante iff => Ramk(A) = Ramk(A) @ Uniqueness ?- linear system has one solution iff => Romk (A) = Ramk (A) = n 3 infinitly & many solution iff => Rank (A) <n (4) NO_ solution &- linear System is in- consistant iff @ Rank (A) & Rank (A)

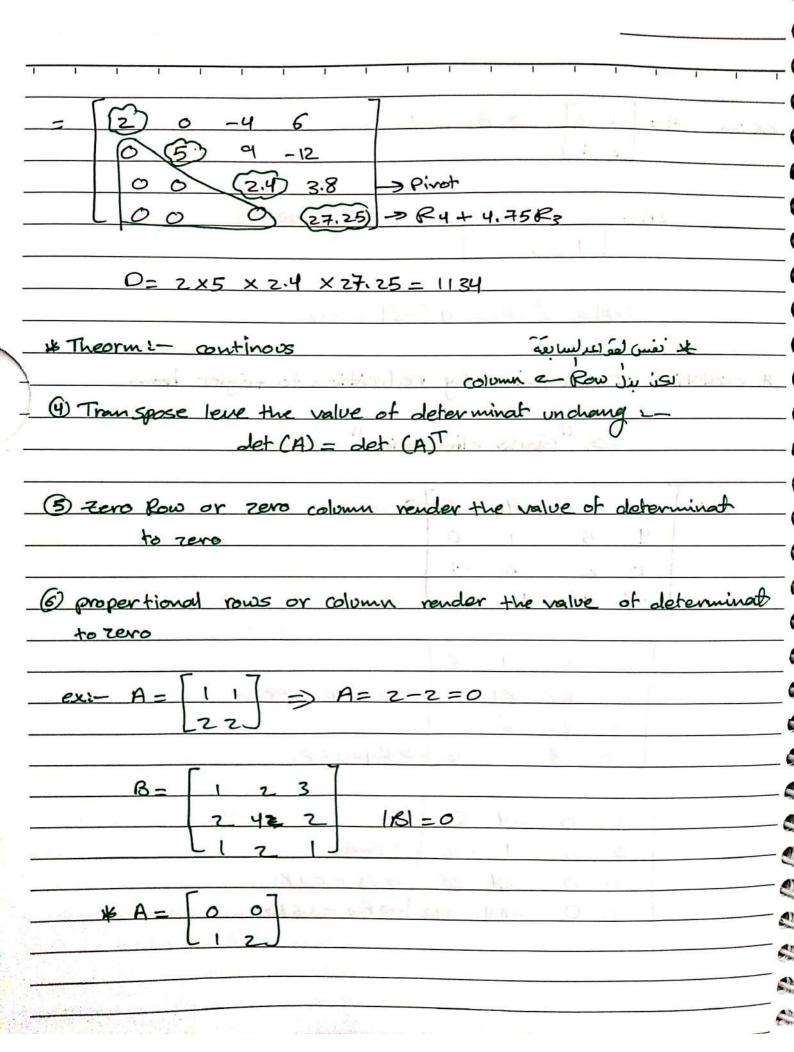
2267 14 727			25/	2/2020
reference and		1 1	Le	C- 13-
	10.		1473	, , ,
D = det A = 911 912 913	stor Head	5 d	1. 1.	and the second
921 922 923	Pr.			
931 932 933	12/2	30)3	11-	/-
	2,411	4 2 1 3	T T	
= + 911 922 923 - 912	1 921	923 +	913 921	q2Z
932 933	931	a 33	1 931	932
10 10 10 10 10 10 10 10 10 10 10 10 10 1	and a chief		. J	104
= 911 [922 933 - 923 932] -	912 [921 a	132 - 923	931] + 913	azi azz - azza
	22. 4. 10	1 -1	T	
O1 - b1 912 913	211.	No.	1 10	
b2 922 923				
b3 932 933		14	1 10/3	
		<u>-\</u>	7.	
= b1 922 923 - 912	b2 923	+ 913	· 62 922	
932 933	b3 a37		b3 932	
1982 -138	-2 -121		c	- Ai
			ar mbol	
Dz = 911 b1 913				
azı bz azz				
1 931 bs 932			111111	E +1.
		فتق إلى	13.13	
= 911 bz az3 - b1 921	923 .	+ 913 9	zı bı	
b3 933 931			A31 b2	glig.
	1331		1	
D3 = 911 921 b1				
921 922 bz				
931 932 b3				
= 911 azz bz - azı a	21 b2 A	- by a	21 922	
932 62 9:	.		31 923	
	1 60 1			
			25	
		1 1	1 1	Five App

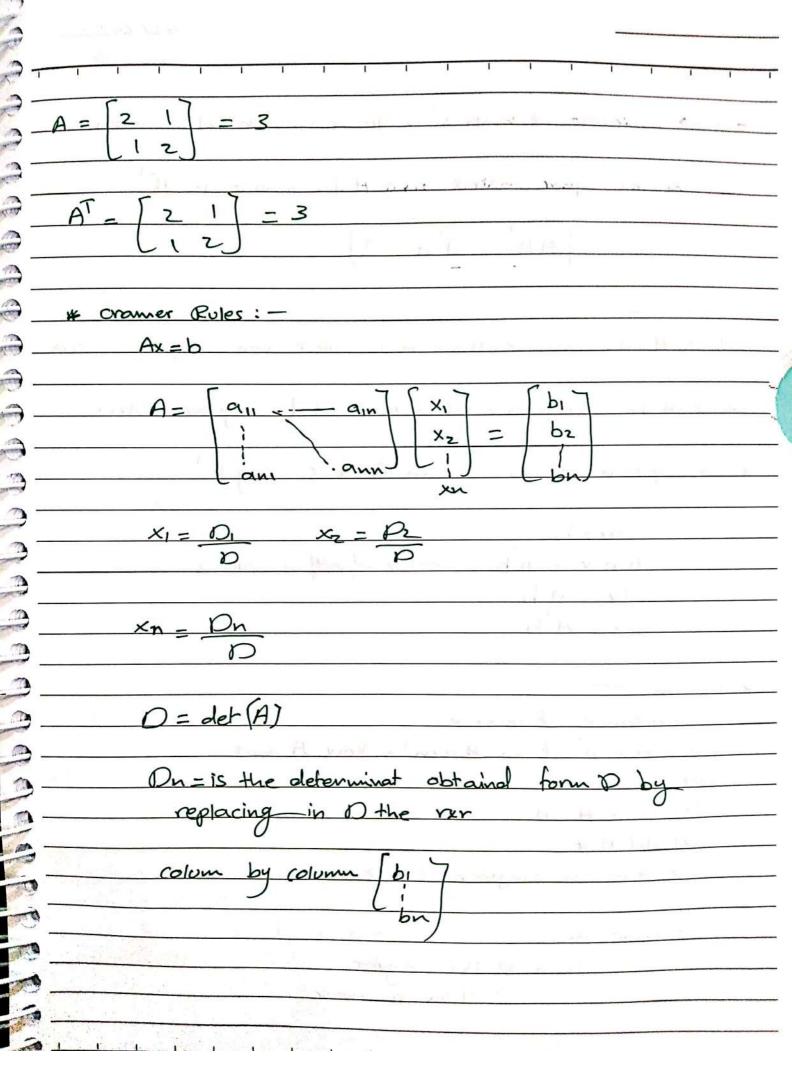
25/2/2025					27/2/20	120
		-,			Lec-14-	
1 1 1 1	1 1 1	1 1 1	1 1	1 7	1 1	1
7.7 > deter	mainsat + cu	comer Rule	s i—		to be last	
		V V	1 12	3		
A -	[a11 a12	913		191		
	921 92					
		A.		Di v l		
	931 032	2 4351				
0 11 0		5 5 1	1.	1 0.5	921 022	
D = der H:	= au azz			II.		
Total Company	932	a33	981 933		931 932	
+			1			
1/2 The mine	or matrix o	of A calle	N :-	<u> 11 21 21 21 21 21 21 21 21 21 21 21 21 </u>	2 2 2 2 2	P. 16
·		7		LL VIII	*	
	44 H12 F	100		hi had	No. 1	
	421 HZZ A					
	M31 H32 1	433	gerfin	3 x 5 y 3	rat -	
100	<u> </u>	do d		14.15 A	10 L	
$\mathcal{M}_{1} = \mathcal{M}_{2}$	22 23	= 922 0	33 - 9230	132		
Water Tarent Control of the Control	132 a 133		1			
L a la						
Mz=	921 923	= 021 93	3 - 923 9	31		
	931 933					
	ार्च प्राप्ते श	6 4 1111	mill will —	3-5 1	y land w	
M3 =	921 922	= 921 a	32 - 922	a31		
	2 031 932					
			1		infll	
			Lyri	2.484	311	
	Yalada a		100	S (F)	11	
	W ₃ (1)				100 Table 30	

1 1 1		
& the cotar	ctor matrix of A is	called C ??
	1 1	
C= C	CII CI2 PC13	
(C21 C22 C23	- 4
	C31 C32 C33	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
	:12	
ز	$\kappa = (-1)^{i+k}$ Hix	= bep
	-	10- 57
C =	M11 - M12 M18	
	-M21 M22 -M23	
	L MSI -M32 M33	
		Y
	A->H->C	
Theorn :-		
	167	A. C. C. L. A. C.
	change of two row	as Kullander Multiplies the valu
(1) Inter	V	as Kullander Multiplies the valu
1 Inter	change of two row determinat by (-1)	as known Multiplies the valu
1 Inter	determinat by (-1)	
① Inter of a	determinat by (-1)	w to another now does not often
① Inter of a ② addit	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not often
1 Inter of of addit	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the
1 Inter of of addit	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not often
1 Inter of of addit	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the
1 Inter of o	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the
1 Inter of o	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the
① Inter of ② addite +he ③ Multip	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the
① Inter of o	determinat by (-1) ion of Multiple of rou e value of determina	w to another now does not alterate. on zero constant (c) Multiply the

ext $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ $B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$	217
A = 1 - 4 = -3 $B = 3$	4-1=3
	, <u>33 l 38 g 15 i</u>
ex:- A= [12] -> A=1-	4=-3
L21	
	a sill that is pin
= 12 +> Airot	
0-3->R2-ZR	had the sale of the sale
	sala - sala - plas
= -3 -0 = -3	1 1/2 1/2 1/2 1/2 1/2 1/2 1/2 1/2 1/2 1/
ex:- A=[12] -> A=1-	- 4 = -3°
L21J	
	- more market
B=[24] -> B= 2	-8=-6 = 2[A]
heavished [[115] the value	
	(b) of trained to
* Rule :-	
det [CA] = c" det	SATA SHIPLE IS WITH A
	decimandal de sous ser
-> A = Matrix	
c = Schlan	most the track to be the start to
the same of the sa	And hiden wish is some
	** U
The state of the s	
A CONTRACTOR OF THE CONTRACTOR	

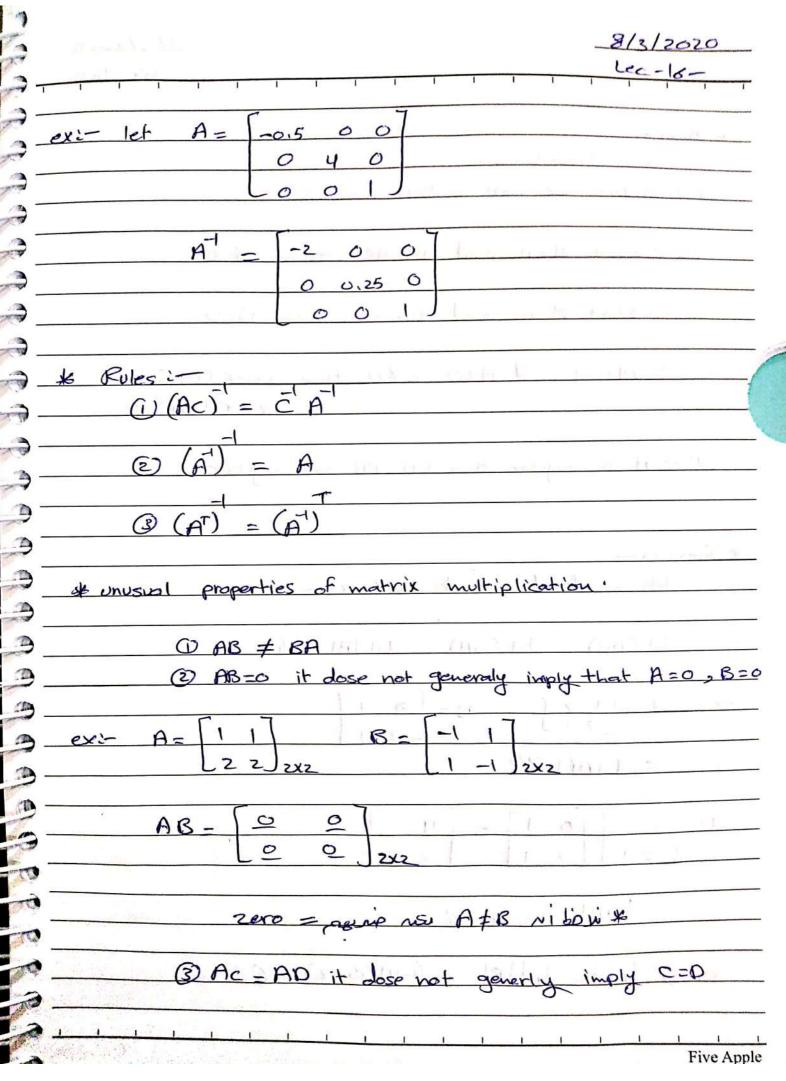
$ex = A = \begin{bmatrix} 1 & 2 \end{bmatrix} \rightarrow A = 1 - 4 = -8$
21)
+ 1-10-y- 7-19-32-6-1
$2A = \begin{bmatrix} 2 & 4 \end{bmatrix} - 9 & 2A = 4 - 16 = -12$
<u> </u>
1814 - 5 - As x R x 5 x 8 - x
$ zA = 2^2 A = 4[-3] = -12$
de in the probability special transferral to
evalution of determinat by reducation to trigler from
€ "Gauss elimination" €
= Gauss eliminariam
0= [2 0 -4 6] Pivot
7 4 5 1 0
0 2 6 -1
Therimas 1 -3 80 p. 9 - roled musics we star bustoning to
enar er
= 20-46
0 25 19 -12 > R2 - 2R1 - Privat
0 2 6 -1 0 8 3 10 => R4+1.5R1
0 8 3 10 J = K4+1.5R1
= 20-46
0 5 9 -12 - Pivot
0 0 24 38 -> 83 - 0,4 R1
00 -11.4 29.2) → Ry - 1.6 K2





	5/3/2020
	Lec - 15-
 	
7.8 -> Inverese of matrix, Gauss Jon	D 1
> For squar matrix nxn Ait's in	nerse is A-1
AA' = A'A = I	Ls / J
Note:	-: estable recorded of
(1) if A has inverse than A is called	non_singular matrix
@ if A has no-inverse than A is called	singular matrix
* For system Ax = b we can find X .	using ATI
Ax = b	(A) = 18.
Ax=b A'Ax = A'b C rundy	المرد المرد الم
$Tx = A^{-1}b$	• •
$x = A^{\prime}b$	NJ - 12
X = 11 D	
# Theorn :	
existance of inverse.	(N) tol = 1
the inverse A of an known matrix A	exist
iff and a most landertie temperature	ode zia deb
(i) Rank A=n	Prince
@ det A \$ 0	V
3) A is non-singular.	PO PALIS
	\
if rank Acn	
than @ A is singular	
@ A has no imprese	
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	

,			5/3/2020
	400		Lec - 15
- -			
-	=> Find	ling invers of matrix by Gauss - Jord	an elimination
_	ext-	let A - [-1 1 2] 3 -1 1 -1 3 4	
_	Balutio	on =)	
	Ã=	$ \begin{bmatrix} A:IJ = $	-> Pivot
) -) -) -	= -	-1 1 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
• - -	= [-1 12 1007	
) _		027,310	
) _	L	00-51-4-11) R3-RZ	
9_		<u> </u>	11 1 1
9	=	+1 -1 -2 -1 0 0 -R1	
3		0 1 3.5 1.5 0.5 0 -> 1/2 PZ	
9.	16-toria	0 0 1 1 0.8 0.2 -0.2 > 0.2 R3	
D.		- Ann -	
3		_ ,	
0			+2R3
0			-3.5R3
0		L 6 0 1 0,8 0,2 -0,2	
		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	<u> </u>
_			
		AND THE RESIDENCE OF THE PARTY	



or = |AB| = |A|B| = (1-4)(0-2) = 6

8/3/2020 (i) adj (A) = [cof(A)] @ A [adj (A)] = [adj (A)]A = det(A) I [adj (A)] IAI

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(2) by find 2 Deigen value we substitue in (A-71)x=0
to find eign vector X

exi-

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0

let $A = \begin{bmatrix} -5 & 2 \end{bmatrix}$ Find eigen value of and eigen vector?

@ def (A - XI) =0

$$\begin{bmatrix} -5 & 2 \\ 2 & -\frac{\pi}{2} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 0$$

$$\begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = 0$$

$$\begin{bmatrix} -5-\lambda & 2 & = 0 \\ 2 & -2-\lambda & 4 \end{bmatrix}$$

(-5-2)(-2-2)-4=0

$$(\lambda + 6)(\lambda + 1) = 0$$

$$\lambda = -1$$
 $\lambda = -6$

For $\lambda = -1$ \Rightarrow the cross pointing eigen vector is $X = (A - z I) \times = 0$

$$\begin{bmatrix} -\mathbf{2} & \mathbf{4} & \mathbf{2} \\ \mathbf{2} & -1 \end{bmatrix} \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{6} \\ \mathbf{0} \end{bmatrix}$$

$$\begin{array}{ccc} X_1 = 1 & \hat{X} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \\ X_2 = 2 & 2 \end{array}$$

for
$$\lambda = -6 \Rightarrow$$
 the cross bonding eigen vector x
is $(A - \lambda I)x = 0$

$$\begin{bmatrix} 1 & 2 & \begin{bmatrix} x_1 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_2 \\ \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{array}{ccc} X_1 = Z & \hat{X} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \\ X_2 = -1 & \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

* normaliz of x:-

$$||x|| = \sqrt{x_1^2 + x_2^2 + x_3^2 - \dots + x_n^2}$$

$$norm (x) = x = 2$$

$$|x|| \sqrt{5}$$

$$|x|| \sqrt{5}$$

Lec- 18-

ex: - Final eigen value and eigen vector? For

O def (A-λI) =0

-

1

$$\begin{bmatrix} -2 - \overline{\lambda} & 2 & -3 \\ 2 & 1 - \overline{\lambda} & -6 \\ -1 & -2 & -\overline{\lambda} \end{bmatrix} = 0$$

$$-\lambda^{3}-\lambda^{2}+21\lambda+45=0$$

$$\lambda = 5, -3, 4$$

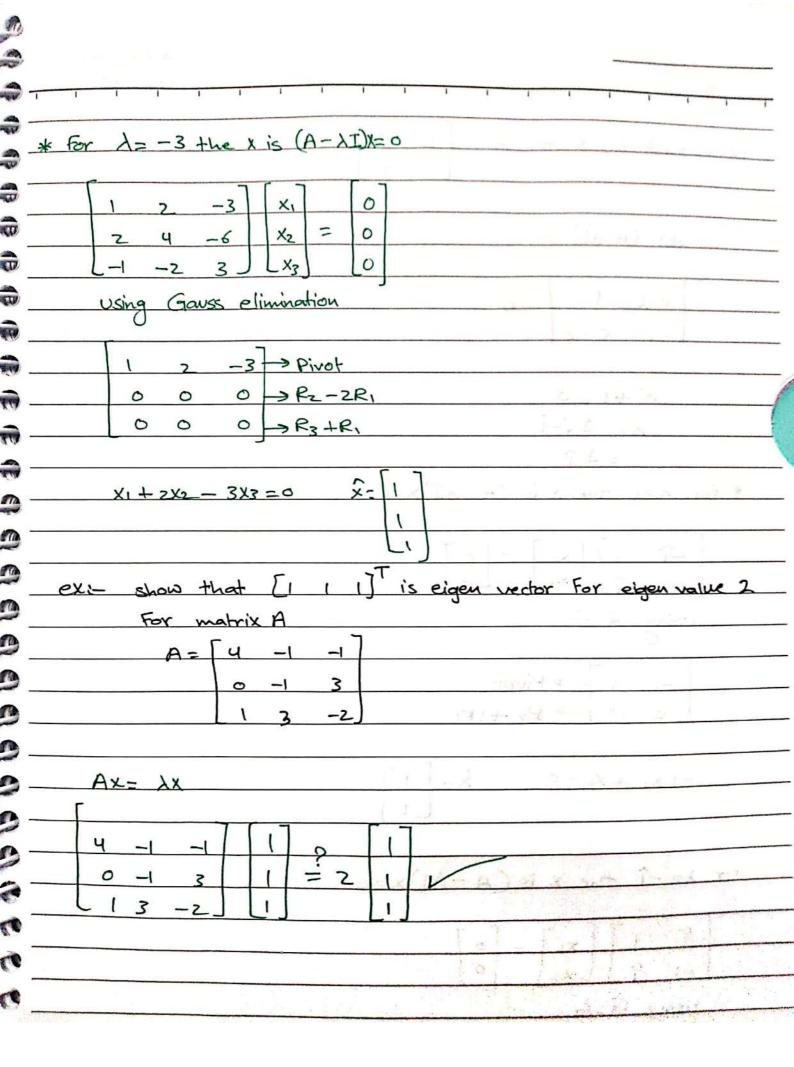
* For $\lambda = 5$ the cross ponding vector x is $(A - \lambda I)x = 0$

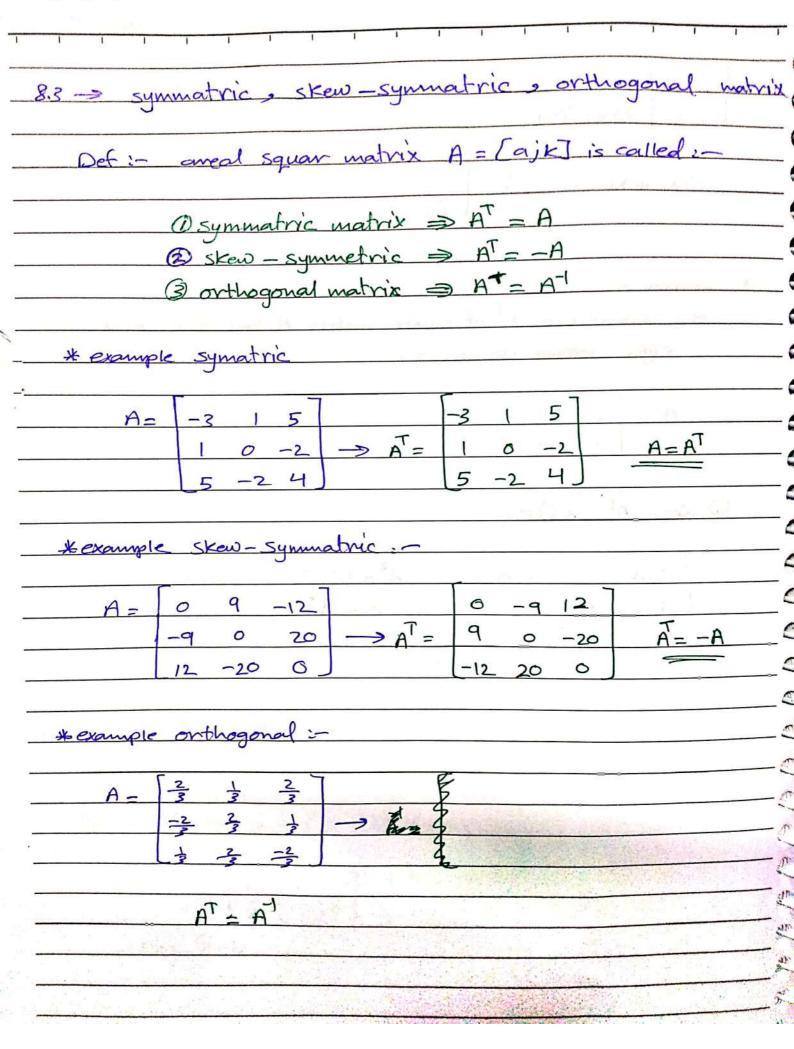
	7 7 7			Γ -		
-7	2	-3	Χı		0	1
2	-4	-6	× ₂	11	0	
	-2		_X3_		0	J

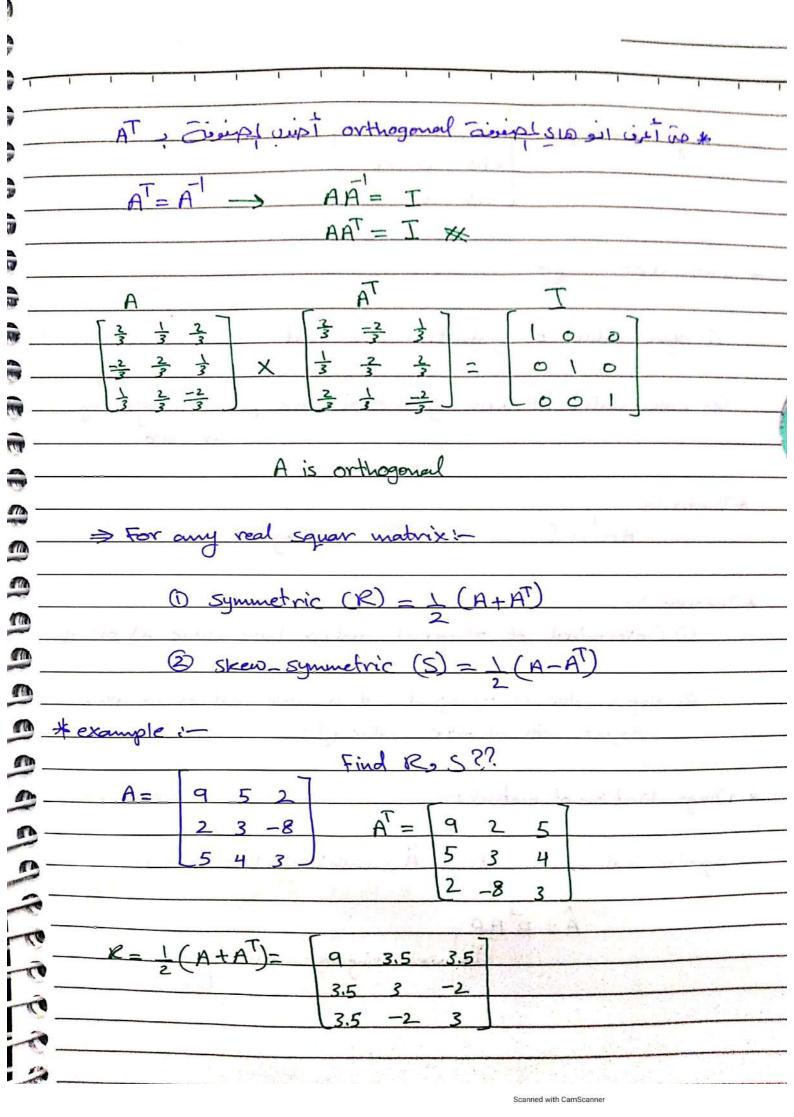
using Gauss-elimination:

-7	2	-3	7-> pivot
 0	-24/7	-48/7	-> R2 + 3/7 R1
	-16/7		-> R3 - 1 R1
		- 13.14 <u>1</u> .14.14.14.14.14.14.14.14.14.14.14.14.14.	7

1 1 1 1 1 1	1 1 1	1 1 1	1 1
= -7 2 -3		And the second or	F.1. 10 10 10 10 10 10 10 10 10 10 10 10 10
0 -24/7 -48/7			
0 0 0	-> R1 - 3/2	1	
$-7x_1 + 2x_2 - 3x_3 = 0$			
-24 x2 - 48 x3 =	9		
7 7		3.	
$1et X_3 = -1 X_2 = 2$	X,=l	x=[1]	
-		2	3 7 3
**************************************		1-1	- 1
			A = 2
	` \ T\		
* for \ = -3 + he x is:- 1	$A - \lambda I \lambda x = 0$	3	2
7 (, 7	r 7		4 / 4
1 2 -3 X1	0	1	
2 4 -6 X2 =	0		
		1 3 dl8 + k	54 5- 6
using Gauss eliminal	ion	0.	100 July 10 Ju
1 2 -3 Pivot	COL 100	hymid carlos	and the second
0 0 0 PZ-2			
() 0 0 > R3 + F		, T.	1
	3		
	7 [,7		
$x_1 + 2x_2 - 3x_3 = 0$	x= 1		
			3
	<u>LJ.</u>	The property of	1
			<u> </u>
		100 C - 100 C	· · · · · · · · · · · · · · · · · · ·
		4.4 A	A







	$S = I(A - A^{T}) = 0 1.5 - 1.5$
	$S = \frac{1}{2} (A - A^{T}) = 0 1.5 -1.5$ $-1.5 0 -6$
-	1.5 6 0
	* Theorem - 2°
	@ eigen value of symmetric are real
	@ eigen value at skew-symmetric are pure imaginary
	or zevo
-	Lungary from the
-	AAT=I onthogonal
	AA = 1 , AA = 1 onthogonal
	* Theorem:
-	1) Determinat of othogral matrix have value +1 or
	The second secon
	@ eigen value of othogral matrix are real or comple
	conject with absolute value (1)
	v Brette at the st
	* Diagonalization of matrice-
	- symilar matrix = matrix A is called similar to uxn
-	Santon many 5 month 12 119 course
	$\hat{A} = \rho^{T} A \rho$
	Is Non-singular matrix
	and the second of the second o

O is similar to A then has eigen value 1) if x is eigen vector for A then A has eigen vector 4= p1 x cross ponding. 4 example in Find the eigen value and eigen vector for A=A ?? A= PAP M det (Â- IX) =0 (h) TA > (A-ZX) =0

(A-3I) y=0 * الحال القيس ك أم نحة أمل مي العزالات A مفق شارفعا في ما ألم ألم المنظيفة الله لمنط نوج * Diagonalization of matrix if an nxn matrix A has basis of eigen vector diagnal matrix = 0 = Z AZ Is eigenvector of A. with column vector * example à 7.3-2 7.3 -11.5 17,7 0 det (A-AI)=0 + (-3.7) -11.5 -11.5 177 ≥= 0,3 -4

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ch 9 91 -> vector : * scalar -> determint by its magnitude (voltage, tempreture, length speed) * vector -> has both magnitude + direction (Force, displacement, velocity) Note :- ① Avector is drawing by arrow a=a per admin vector of 1. ② a' = length = magnitude -> a = \(\frac{1}{2}\) \(\fra
A scalar -> determint by its magnitude (voltage, tempreture, length, speed) * vector -> has both magnitude + direction (Force, displacement, velocity) Note :- ① Avector is drawing by arrow a=a pow about vector of 1. ② lai = length = magnitude -> lal = \(\text{12}^2 \tau^2\) ③ trail is initial point, Tip is a termial point aid abor (1) ali abording ④ lai = a = unit vector ⑤ different length different direction different and d ⑥ component of vector P(z, 41, 21) -> initial point Q(z, 42, 22) -> terminal point
(voltage, tempreture, lengths speed) * vector > has both magnitude + direction (Force, displacement, velocity) Note: (Part = displacement, velocity) Note: (Part = length = magnitude > lal = \(\frac{1}{2^2 + C_1^2}\) (Part = length =
(voltage, tempreture, lengths speed) * vector > has both magnitude + direction (Force, displacement, velocity) Note: (Part = displacement, velocity) Note: (Part = length = magnitude > lal = \(\frac{1}{2^2 + C_1^2}\) (Part = length =
(voltage, tempreture, lengths speed) * vector > has both magnitude + direction (Force, displacement, velocity) Note: (Part = displacement, velocity) Note: (Part = length = magnitude > lal = \(\frac{1}{2^2 + C_1^2}\) (Part = length =
(Force o displacement, velocity) Note 2— (D) Avector is drawing by arrow a=a power object vector of the all = length = magnitude -> a = V(2)/4(1) ² (B) trail is initial point, Tip is a termial point aid abor (-1)/11, with all about (D) a = a = unit vector (D) a = a = unit vector (E) a = a = unit vector (E) a = a = unit vector (E) a = a =
(Force o displacement, velocity) Note 2— (D) Avector is drawing by arrow a=a power object vector of the all = length = magnitude -> a = V(2)/4(1) ² (B) trail is initial point, Tip is a termial point aid abor (-1)/11, with all about (D) a = a = unit vector (D) a = a = unit vector (E) a = a = unit vector (E) a = a = unit vector (E) a = a =
Note 2— ① Avector is drowing by arrow a=a paw odmly vector of In ② a = length = magnitude -> a = \(\tau^2 + 0)^2\) ③ trail is initial point, Tip is a tornial point aid about crivil, white about the control of
(2) A vector is drawing by arrow a=a regulation vector of land a
(2) a = length = magnitude -> a = \(\tau_{12}^{2} \) a = \(\text{length} = \text{magnitude} \) -> a = \(\text{loss} \) a =
(2) a = length = magnitude -> a = \(\tau_{12}^{2} \) a = \(\text{length} = \text{magnitude} \) -> a = \(\text{loss} \) a =
(3) brail is initial point. Tip is a tormial point aid about the first will (4) tall=1 a = unit vector (5) a=b different length different direction different and different point (6) component of vector P(z1, 41, 21) -> initial point (7) (22, 42, 22) -> torminal point
(3) brail is initial point. Tip is a tormial point aid about the first will (4) tall=1 a = unit vector (5) a=b different length different direction different and different point (6) component of vector P(z1, 41, 21) -> initial point (7) (22, 42, 22) -> torminal point
aid aboi (chu), aut about (4) a = 1
aid aboi (chu), aut about (4) a = 1
(a) a =1 a= unit vector (b) a =1 a= unit vector (c) a =1 a= unit vector (d) a =1 a= unit vector (e) a =1 a= unit vector (e) a =1 a= unit vector (e) a =1 a= unit vector (f) a =1 a= unit vector (g) a =1 a= unit
5) 97 b 9 7 10 a=b different length different direction different and direction proportion of vector P(z1, y1, z1) -> initial point Q(z2, y2, z2) -> tornival point
5 component of vector P(z1, y1, z1) -> initial point Q(z2, y2, z2) -> torninal point
5 component of vector P(z1, y1, z1) -> initial point Q(z2, y2, z2) -> torninal point
6 component of vector P(z1, y1, ≥1) → initial point Q(z2, y2, ≥2) → torminal point
6 component of vector P(z1, y1, ≥1) → initial point Q(z2, y2, ≥2) → torminal point
6 component of vector P(z1, y1, ≥1) → initial point Q(z2, y2, ≥2) → tornival point
Q(Z2, 42, 22) -> torminal point
Q(Z2, 42, 22) -> torminal point
then a = [a1 , a2 , a3] a = \(\alpha \frac{1}{492} + 98^2 \)
then a - (a1 , a2 , a3) a = Vai + 92 + 98
91= 22-21 92= 42-31 92-21-31

* example > P=[4,0,2] Q=[6,-1,2] Find component and longth of vector a ?P a= [2,-1,0] $|\vec{a}| = \sqrt{2^2 + 1^2} = \sqrt{5}$ * Assition vector V of appint A (21, 24, 21) is anector with orign (0,0,0) initial point and A is termind point * vector addition + scalar multiplication: O == [a1, a2, a3] b = (b1 = b2 = b3) then -> a+b= [aitbi = az+bz = az+bz] a-b = [a1-b1 = a2-b2 = a3 - b] * Rule :-* a+b = b+a # (0+V)+0 = 0+[V+0] = Q+V+0 * * 2+0-2 vector 2 10 # a + (-a) = zero O scalar = 0 1 0 vector = 0,0,0

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TIP

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_	
_	* scalar multiplication =
_	I was been a first to the second first
-	a= (a1, 92, 93)
<u> 21 :</u>	
-	$C\tilde{a} = [Ca_1, Ca_2, Ca_3]$
_	* Rule :-
	* c[a+b] = ca+cb
	* [c+k]a = ca+ka
_1	* $c[k\tilde{a}] = (c\tilde{a})k = ein(ck)\tilde{a}$
_	* 12 = 2
_	$\alpha = 0$
_	* - a = -a - indication index a point as much
-	,
) . .	* example v
-	$\vec{a} = [4,0,1]$ $\vec{b} = [2,-5,\frac{1}{3}]$
t -	$0-\vec{a} = \begin{bmatrix} -4,0,-1 \end{bmatrix}$
-	()-4 = L 1)-13 = 11 - 13 = 11 - 12 =
-	@ 7a = [28,0,7]
•	
•	3 = + b = [6, -5, 4]
	To a first - 1 60 x 0 1 x 0 + 61 x - 1 x 1 1 2 2
	@ 2[a+b]=[12,-10, 8]
	B2[a-b]=2[2,5,+2]=[4,10,4]
	Carried Carried Control of the Contr

* unite vector: - To Jo R 7=[1,0,0] 1 1- [0,1,0] All R=[0,0,1] example :-== [a, a, a, a] = a, î + a, f + a, k * inner product [dot product] a.b = |a||b| cos 0 ab=zero if a=0 or b=zero 121 = Ja12+ a2-M 1 bh= 1 bi2+bi2-a= [a1, a2, 93] b= [b1, b2, b3] a.b= [a1b1 + a2b2 + a3b3] = من اوجد لذارية. م 0 * example :-2-[1,2,0] b=[3,-2,1] Find Obetween a and 63? 0 = 96.86 COS A = 3-4+0 - -1 \$ 15 114

* unit vector î, î. î @ 1.3 = 0 6 j.k =0 6 F.1 =0 # Rulp !-Rulp:
* (q\vec{a} + q\vec{b}).\vec{c} = q\vec{a}.\vec{c} + q\vec{b}.\vec{c} \quad * a.a = 0 iff a=0 * (a+b) = a.c+b.c * 1a.bl < 1a11b1 * |a+b| < |a|+|b| 12+B1+ 12+B12 = 2 [1212+1612] * vector product [cross product] @ if \a=0, \b=0 then |V| = |\axb| = |\a| |\b| sin\tag{\theta}

A	
-	
) –	0 121 1221
a —	B if O between a, b are zero or 180 V = axb = zero
- -	
	* a= [a, a, 2, 93]
_	B = [h1 2 b2 2 b3]
-	
} _	$\frac{3}{3} \times \frac{5}{5} = \frac{1}{5} \cdot \frac{2}{5} \cdot \frac{2}{5} \cdot \frac{1}{5} \cdot \frac{2}{5} \cdot \frac{1}{5} \cdot \frac{1}$
D _	a. a2 a3 → î (a2b3 - a3b2) - ĵ(a1b3 - a3b1) + k(a1b2 -
<u> </u>	b1 b2 b3
<u> </u>	
<u> </u>	example 2
-	a=[1,1,0] b=[3,0,0]
) –	$\vec{a} \times \vec{b} = \vec{i} \cdot \vec{b} \cdot \vec{k}$
, –	$\frac{2xb-1}{10} = \hat{1}(\frac{2}{3}) - \hat{1}(0) + \hat{1}(-3) = -3\hat{1}$
) –	300 = [0,0,-3]
—	
- 9	
· _	* Note:
_	$\hat{1} \times \hat{1} = \hat{k} \qquad \hat{1} \times \hat{1} = -\hat{k}$
	$3x\hat{\varepsilon} = \hat{1} \qquad \hat{\varepsilon}x\hat{s} = -\hat{1}$
) —	$\hat{1}\hat{x}\hat{k} = \hat{\delta} \qquad \hat{k}\hat{x}\hat{i} = -\hat{\delta}$
-	
9 -	* Rule :-
9 -	$O(L\vec{a}) \times \vec{b} = L(\vec{a} \times \vec{b}) = \vec{a} \times L\vec{b}$
	② 3 x (b+c) = (3xb)+(3xc)
<u>a,</u>	$ (\vec{a} \times \vec{b}) \star \vec{c} = \vec{a} \times c + \vec{b} \times \vec{c} $
Ċ_	$(4) \vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$
<u> </u>	(a) (a) xc + ax[bxc]
¢ _	
4 _	
1.00	The state of the s

* Scalar Triple product :
For vactor, a = [a1, 8a2, a3]
$\frac{\vec{b} = [b_1, b_2, b_3]}{\vec{b}}$
- C = (C1 , C2 , C3)
2-22
(abc) = a. [bxc] · a az as
$ov = [\vec{a} \times \vec{b}] \cdot \vec{c} = a_1 b_2 b_3$
- C C C 3
* abc -> volum of panallel eipied
- 1 a b C -) volum of parallel expired
A volum of tetrahed = I volum of parmallel eiped
vector e le hos cross produte *
scalar e pe mis dot product è k
سريمام السيس كم الون
to example t
= [2,0,3] Find, () (abc)
b=[0,4,1] @ volum of box
= [5,6,0] 3 volum of tetrahelmon
4) are a, b, c linear indepent
The state of the s
m ~ ° = 1 = 1 2 = = 1
$\mathcal{O}(\tilde{a}, h\tilde{c}) = 2 0 3$
5 6 0 = -12 +0 -60 = -72
Taxalxx + Ex ix

@ volum = 1-72 = 72
(3) volum = 1 x 72 = 12
@ are a b , c independent -> - 7270 then it's independent
* vector + scalar function "derivation"
A VECTOR SCHOOL
* vector function (v) -> depend an point p(x, y, 2)
14/2 ~ (x242) - (V1(X2422) 2 V2 (X2422) V2 (X2422)
example - tangent vector
normal vector
YISYMUL VECTOR
C 0 80
* scalar function f = f(x,y,z)
N + V = (11, 10 = 0)
example -> tempreture
pressure
* example \(\frac{1}{2}\text{y}\text{2}\) = 5xyî+ x^2zî+ y^2z^2\(\text{V}\) (vector function
- Brample V R3J3E7 2 3 J
P(x,y,z) = syx x2y + xyz + z2yx (scalar function

	Land Sta
	1
y drevative function	
$ \overrightarrow{J}(t) = \left(v_1(t), v_2(t), v_3(t) \right) $ $ = v_1(t) \cdot + v_2(t) \cdot + v_3(t) \cdot \hat{k} $	
J(t) = vi(t) + v2(t) + v2(t)	
the same of the sa	ليه
$ \overline{\nabla}(t) = [t, t^2, 0] $	
V(t) = Lt, t, 0	
$\vec{v}(t) = (1+2t+0)$	
$= \begin{bmatrix} 1 & 2 & 0 \end{bmatrix}$	
W. O. I I	
$O(C\vec{V}) = C\vec{V}$ $O(\vec{V} + \vec{u})' = \vec{V} + \vec{u}'$	
(1) (1) - (1) + (1)	
Secretary are set of a second	Y
の(は、す)= はずまなす	
$(\vec{u} \times \vec{v}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{v}$	-
(\$\ta\varphi\ta\	
The second section of the second seco	

* partial derivative: $(t) = \left[V_1(t), V_2(t), V_3(t) \right]$ dv(t) = dv î + dvz î + dvs î dtm dtm dtm dtm (2) second partial drivitine drit den den den * example : let \(\ti, t2) = a cost, \(\) + a sint, \(\) + t_2 \(\) Find Odr Odr Odr Odr Odr Odr Odr - -asint, î + acost, î + or M dt M d el el 16 6 6 2) dr = 0î + 0ê + k 3 dr = -acost, î - asinti (1) dr = 0k

example :let r(t1, t2) = a cost, i + a sint, i + t, t2 k -@ dr 3 dr2 Find O dr dtz dEI 0 -a sinti 1 + a costi + tzk 0 dr = dti = 0î + 0ê + t, E dtz - dr (t, 2) -a sint, i + a cost, it dti(dt) dti * Gradiant of scalar field grad [F] = $\nabla F = \int df$ Five Apple

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* DF= Nables f $V = \frac{d}{dx} + \frac{d}{dy} + \frac{d}{dz}$ * scalar function OF , vector function det f(x=y==) = 232 + 4x= + 3x find & F 9? = df ? + df ? + df ? = (42+3)1 + (6y2)2 + 42 R 0 = 71 + 62 + 42 = (7,6,4) M (10101) M M # directional derivative = grad F [91,92,93] = Vait 92 + 92 grad F = of of of de · = dot product

sk example : Find the direction derivitive of f(x242=) = 22+342+22 P=(2,1,3) in a direction a=[1,0,-2] [1,0,-2] [4x,6y,22] = 15 [8+0-12] = -4 & Gradient of surface normal vectors & unit of normal vector = n = OF * example Find unit normal vector in if f(x24,2) = 4(x2+y2)-22 at point P= (1,0,2) [8x, 8y,-22] = [8,0,-4] **180** 53

* Laplace equation > $\nabla^2 f = \frac{df}{dx^2} + \frac{df}{dy^2} + \frac{df}{dz^2}$ 52 = colled nable see squar let f(x,yot) = 4(x+y2)-22 find q2f 88 08 = [8x, 84, -22] =[8,8,-2] = 8+8-2=14 * divergence of vector field: let \$\frac{7}{x,y,2} = (M, V2, V3) V17+ V23+ V3 R div (v) = q v [dx, dy d]. [v, v, v, v] * vector function -

M

M

M

On

-y22 find div(0) 2×4 0 32 + 2x + (- 2y2) * div (Gradf) = VF As Curl of vector fieldir let = (v1, v2, V3) cm(2) = 7XV

example let = [yz, 32x, 2] find our = ?? -3[0-y] + R[32-2] 4 curl (of) = 0 * div (cm = 0 Rue -> 0 V(fg) = FOg + gof @ of (f) = gof - FDg @ div(FV) = Fdiv(V) + V, OF @ div (Frg) - Fog + of. 79 6 div [grad(f)] = of 6 02(fg) = gv2f+20f,0g+Fo2g (f) = VFXV + F cm/V B div (tixt) = v. am(ti) - ti.cum(ti) * Scalar Field VF , vector field

* scalar Field VF , scalar field

* vector Field div V , scalar Field

* vector Field cm V , vector field

* vector field d/dt, vector field

* vector field d/dtm vector field